







EC-Earth4 - initial scalability and performance on BSC-MareNostrum5

Eric Ferrer - Gilbert Montané Roc Salvador - Marcel Cases

Deploying EC-Earth

Steps to use a new system:

- 1. Deploy and run
- 2. Reproducibility
- 3. Performance, coupled and by component (scalability)
- 4. Optimize coupled performance (balancing)

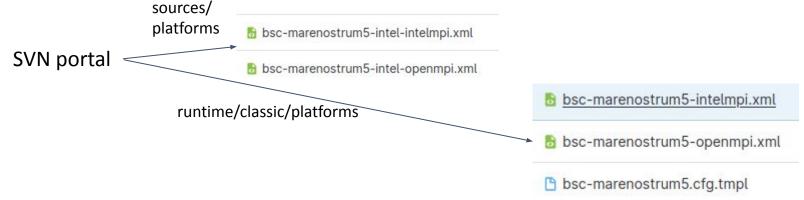






Deployment of EC-Earth

- Create all the compilation and configuration files needed
 - EC-Earth3 (OpenMPI and IntelMPI options):



EC-Earth4 (only OpenMPI):

```
SMHI GitLab _______ bsc-marenostrum5-intel+openmpi.yml
```





EC-EARTH 3 Repro test

• Bit to bit reproducibility -> not achievable

Target -> statistical reproducibility





EC-EARTH 3 Repro test

- Bit to bit reproducibility -> not achievable
- Target -> statistical reproducibility

How to ensure it?

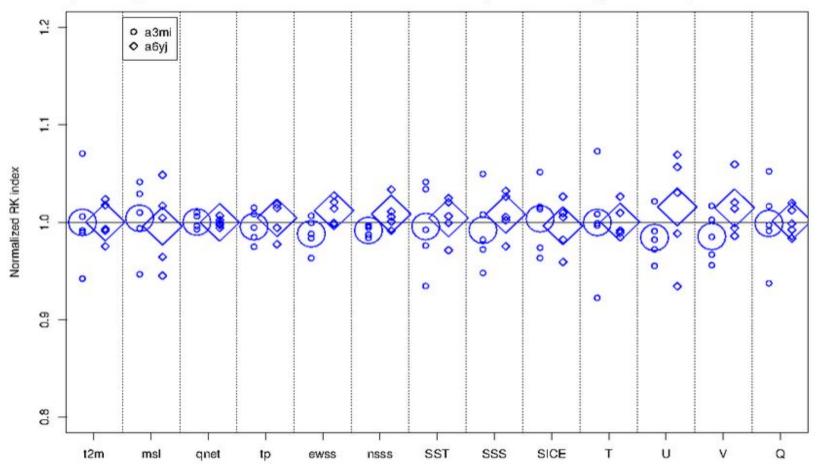
- 5 member 20 year long ensemble
- Compare important variables with baseline reference





EC-EARTH 3 Repro test

Reichler-Kim normalized index Symbols appear in red when ensemble distribution statistically differ according to a KS test, otherwise in blue

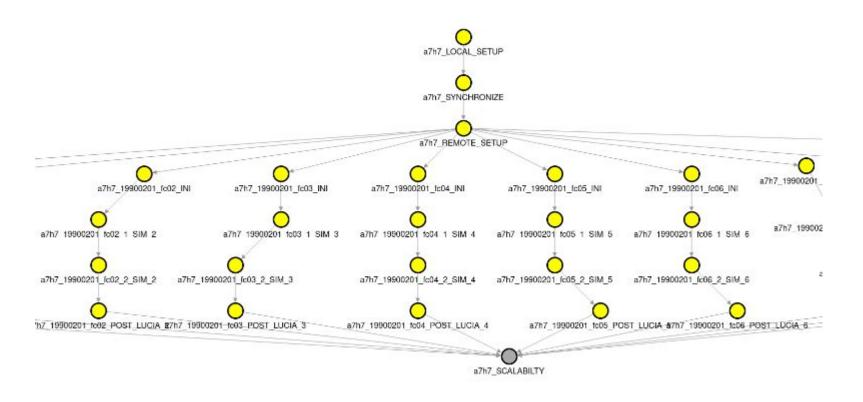




Massonnet, F., Ménégoz, M., Acosta, M., Yepes-Arbós, X., Exarchou, E., and Doblas-Reyes, F. J.: Replicability of the EC-Earth3 Earth system model under a change in computing environment, Geosci. Model Dev., 13, 1165–1178, https://doi.org/10.5194/gmd-13-1165-2020, 2020.



EC-Earth 3 Auto-Scalability



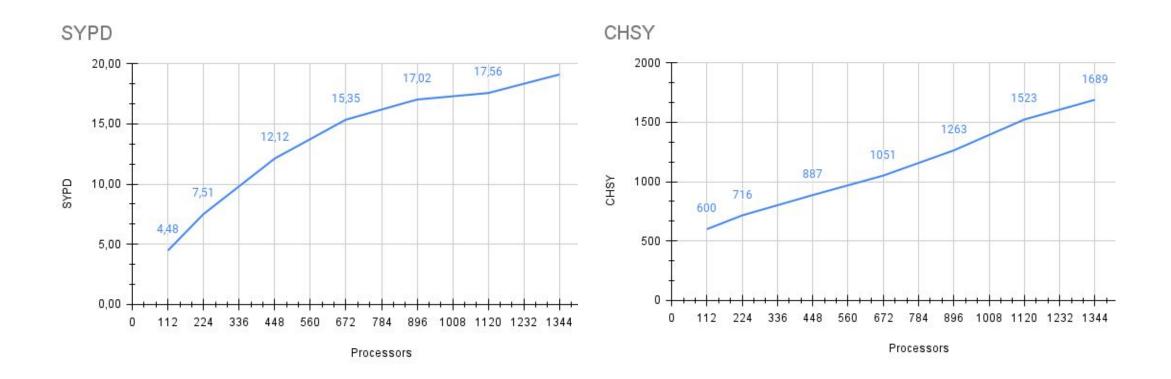
- One experiment does everything
- Based on Lucia tool to automatically obtain data* for:
 - NEMO & IFS
 - Individually & Coupled

*SYPD, CHPSY, coupling cost, wait time





EC-Earth 3 (TL255L91-Orca1) Coupled Scalability

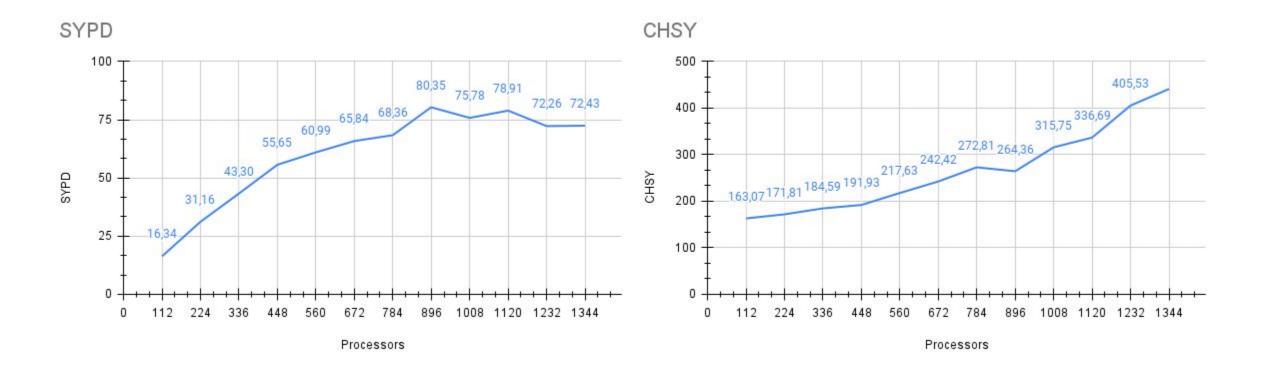




*Unbalanced, CHSY are not representative of what can be obtained when scaling up with balanced configurations



EC-Earth 4 (TL159L91-eOrca1) Coupled Scalability

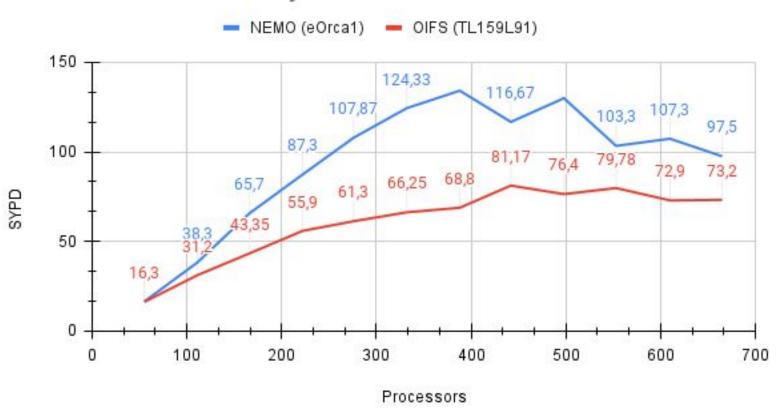




*Unbalanced, CHSY are not representative of what can be obtained when scaling up with balanced configurations



NEMO & OIFS scalability on MN5

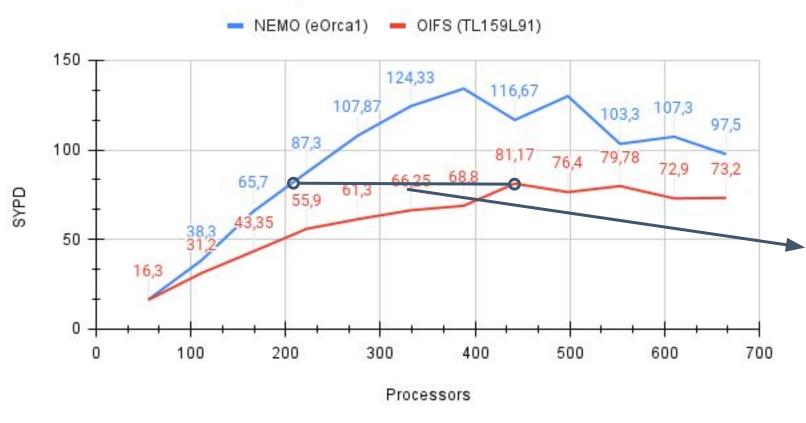


 Lucia provides the individual scalability from a coupled run.





NEMO & OIFS scalability on MN5



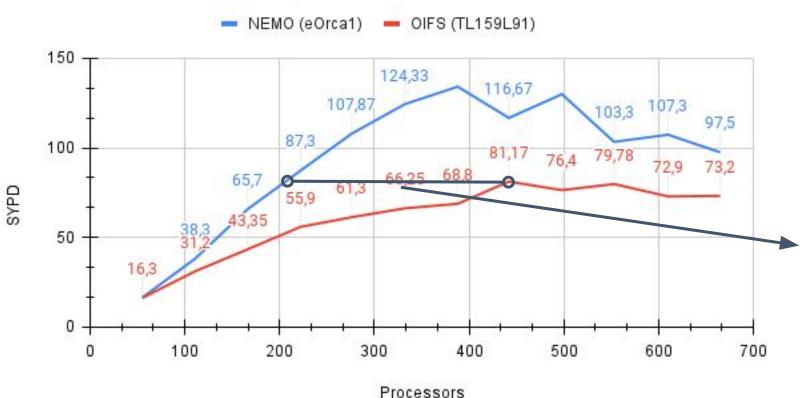
Similar OIFS & NEMO performance:

- OIFS 444 processors ~ 81 SYPD
- NEMO 222 processors ~ 87 SYPD
 Expected Coupled SYPD: ~ 81 SYPD





NEMO & OIFS scalability on MN5



Similar OIFS & NEMO performance:

- OIFS 444 processors ~ 81 SYPD
- NEMO 222 processors ~ 87 SYPD
 Expected Coupled SYPD: ~ 81 SYPD

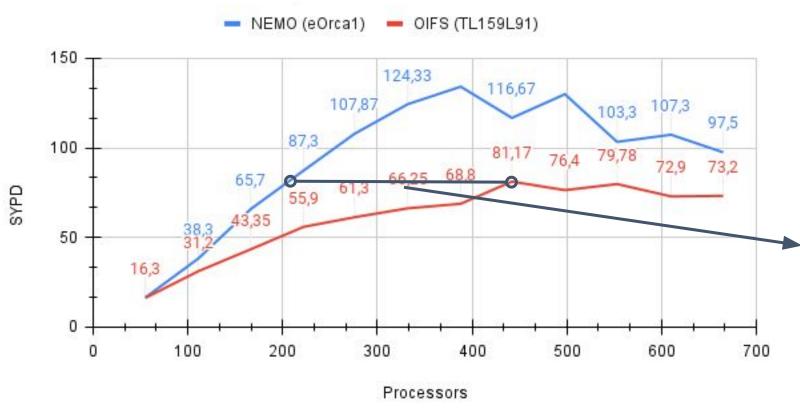
MN5, results ~2 month later with same configuration:

NEMO - 88 SYPD & OIFS 73 SYPD Obtained Coupled SYPD: ~ 71.9 SYPD





NEMO & OIFS scalability on MN5



Similar OIFS & NEMO performance:

- OIFS 444 processors ~ 81 SYPD
- NEMO 222 processors ~ 87 SYPD
 Expected Coupled SYPD: ~ 81 SYPD

MN5, results ~2 month later with same configuration:

NEMO - 88 SYPD & OIFS 73 SYPD
Obtained Coupled SYPD: ~ 71.9 SYPD

Why?

- Coupling cost
- MN5 state variability
- Better balancing required





Fine-tune components performance

run efficiently -> balance multiple components

Manual way -> back and forth runs analyzing results while changing processors for each component





Fine-tune components performance

run efficiently -> balance multiple components

Manual way -> back and forth runs analyzing results while changing processors for each component

Automatize it -> create a workflow that does it -> Auto-LB





Future Work

Compare similar resolutions ECE3 vs ECE4 in MN5

Compare MN4 vs MN5 with same ECE3 configuration

Adapt auto-scalability and auto-lb to use them with ECE4

Adapt reproducibility scripts to use them with ECE4













Thank you

Eric Ferrer - Gilbert Montané Roc Salvador - Marcel Cases

eric.ferrer@bsc.es